

# ACTUATORS TYPE P5/R5 INTEGRATED WITH SMART POSITIONER

### **APPLICATION AREA**

The diaphragm multi-spring pneumatic actuators of P5/R5 type are applied for control operation of control valves and other positioning elements in industrial automatic systems. They are dedicated to collaborate with an integrated smart positioner type SPIROSTER 07 manufactured by the Zakład Automatyki Przemysłowej INTEC from Wrocław.

#### **FEATURES**

The P5/R5 actuator:

 completely reversible action, option to change spring range w/o extra parts,

There are three design options of the actuators:

direct action (air - advances the steam)
 reverse action (air - retracts the steam)
 type P5,
 type R5,

direct action, handwheelreverse action, handwheeltype P5N,type R5N

 no external piping with pulse lines between the adjuster and the actuator for both P5 and R5 options. All the interconnection for feeding and control air are performed via internal channels of the adjuster and the actuator. It eliminates the need to use pulse pipes that must be made of materials suitable for operating conditions of the actuator and eradicates the risk of possible damages during transportation and operation.

- totally eliminated penetration of ambient air into interior of the actuator, which is crucial for improving durability of its diaphragm and extends lifetime of sealing.
- mechanical link between the adjuster and the actuator steam comprises no levers and is installed in the safe way that prevents from mechanical damages and contaminations,
- mechanical, rotary indicator of the valve opening,
- suitable for heavy-duty conditions, such as corrosive agents, potentially explosive atmosphere or aggressive chemicals. All internal parts are made of stainless steel. The cast yoke is protected against corrosion by coating with epoxy powder paints,
- high insensitivity to shocks and vibrations due to reliable mounting of the adjuster and reduced number of connecting and fixing parts,
- possible application of top-mounted handwheel,
- conformity with relevant EU directives concerning the product.



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#### THE ELECTRO-PNEUMATIC ADJUSTER SPIROSTER 07:

- fuzzy-logic, intelligent algorithm for positioning (FUZZY PID),
- contactless measurement of the actuator position with use of a resolver,
- current loop control signal (4 ... 20 mA) or controllability via local networks (MODBUS, PROFIBUS, etc.)
- feedback signal 4...20 mA,
- binary signals of limit positions,
- local and remote control,
- tightening of fittings by clamping,
- automatic, non-intrusive settings of limit position,
- possible splitting of positioning range,
- automatic, adaptive adjustment of dynamic parameters for the actuator,
- internal PID controller for the adjustment process the actuator can operate as an independent, autonomous controller of a process,
- piezoelectric electro-pneumatic transducer,
- customized characteristic curves for the adjustment process.

#### **OPERATION PRINCIPLE**

Operation principle of the actuator is illustrated on drawings Fig. 1, 2 and 3.

The feeding air is delivered via a pipeline to a pressure coupling (13) and then via internal channels (1) to the adjuster (2).

The control air from the adjuster is forwarded to the channel (3) in the actuator yoke.

Further direction of airflow depends on positions of screws (4, 5) and desired function of the actuator.

For the R5 actuator of inversed operation (Fig. 1) the air is forwarded directly to the pressure chamber (6). The non-pressure chamber (7) is connected to channels (14) and vent plug (10) via the opening (8) in the actuator rod and the guiding sleeve (9).

In case of the P5 actuator of direct operation (Fig. 2) the control air penetrates via a guiding sleeve and an opening in the actuator rod to the pressure chamber whereas the non-pressure chamber is connected directly to a vent (14, 10).

The vent passage (14) is connected with interior of the adjuster by the channel (15) (Fig. 3).

If a check valve (16) is installed instead of the vent plug (10) then the non-pressure chamber is isolated from the ambient atmosphere and is supplied solely with pure air from the adjuster.

Switchover of the actuator function is possible when the device is in service with no additional parts or specialized tools.

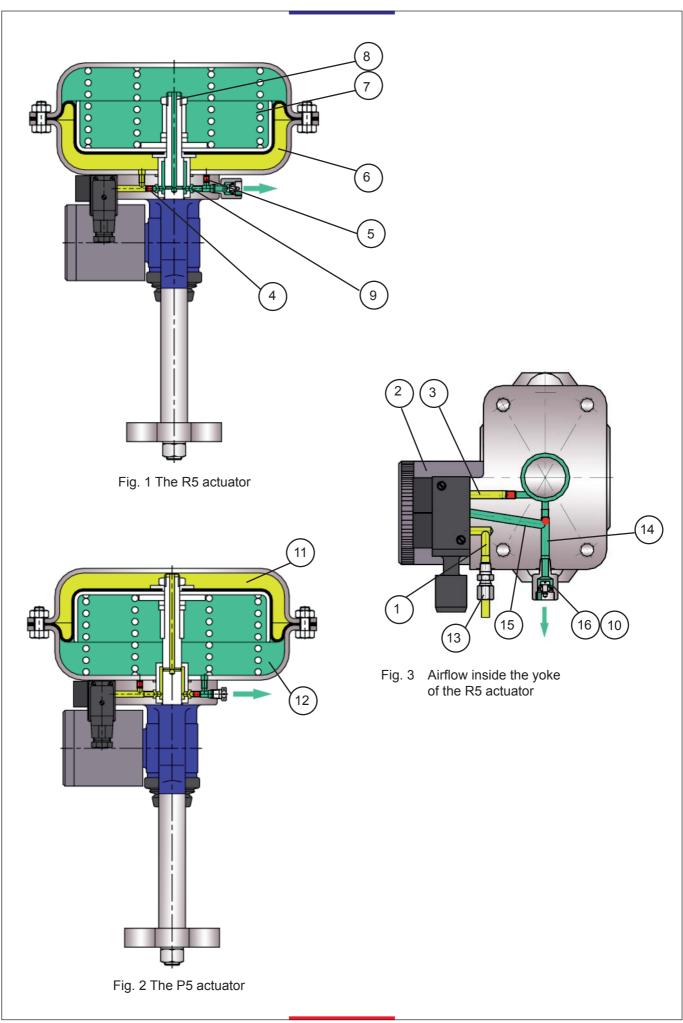
## **TECHNICAL PARAMETERS**

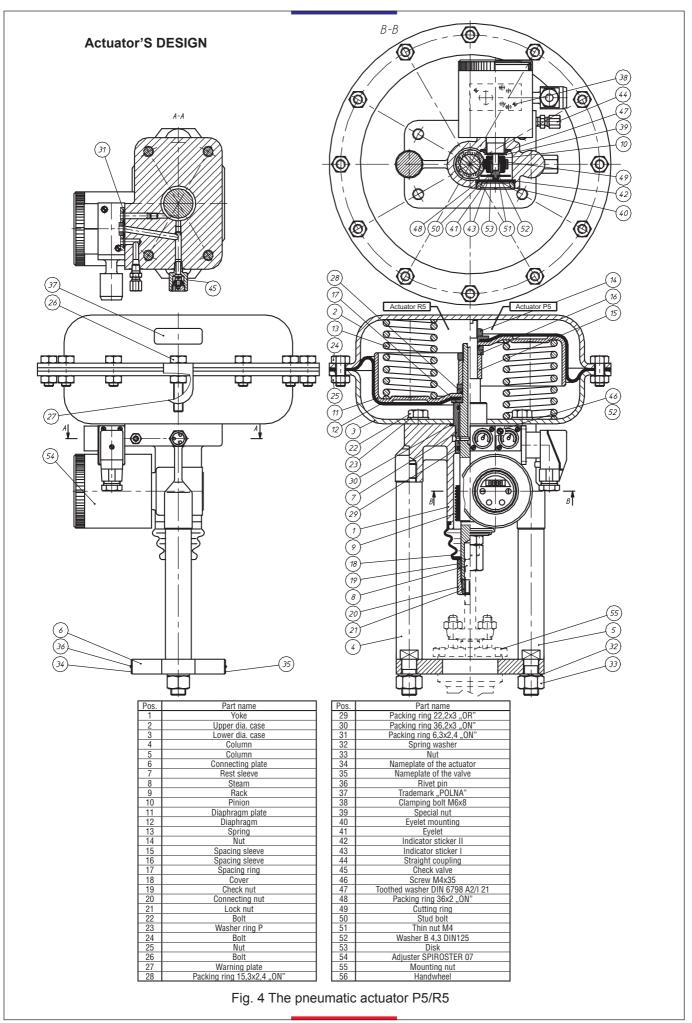
- input signals range:

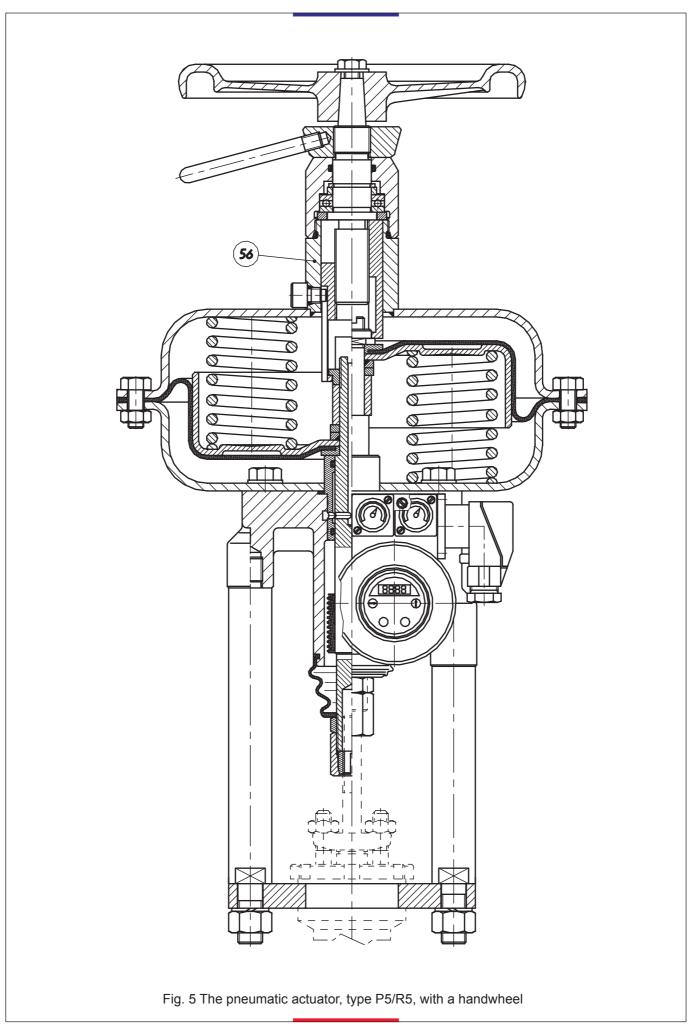
20...100 kPa; 40...120 kPa; 60...140 kPa - 3 springs 40..200 kPa; 80...240 kPa; 120...280 kPa - 6 springs 180...380 kPa - 12 springs

maximum supply pressure: do 600 kPa
 working temperature: - 20...+70°C
 relative humidity: max. 98%

Active area of the membrane	Stroke	Spring range	
[cm <sup>2</sup> ]	[mm]	[kPa]	
250	20	1 6	
400	20	16	
630	20; 38	17	







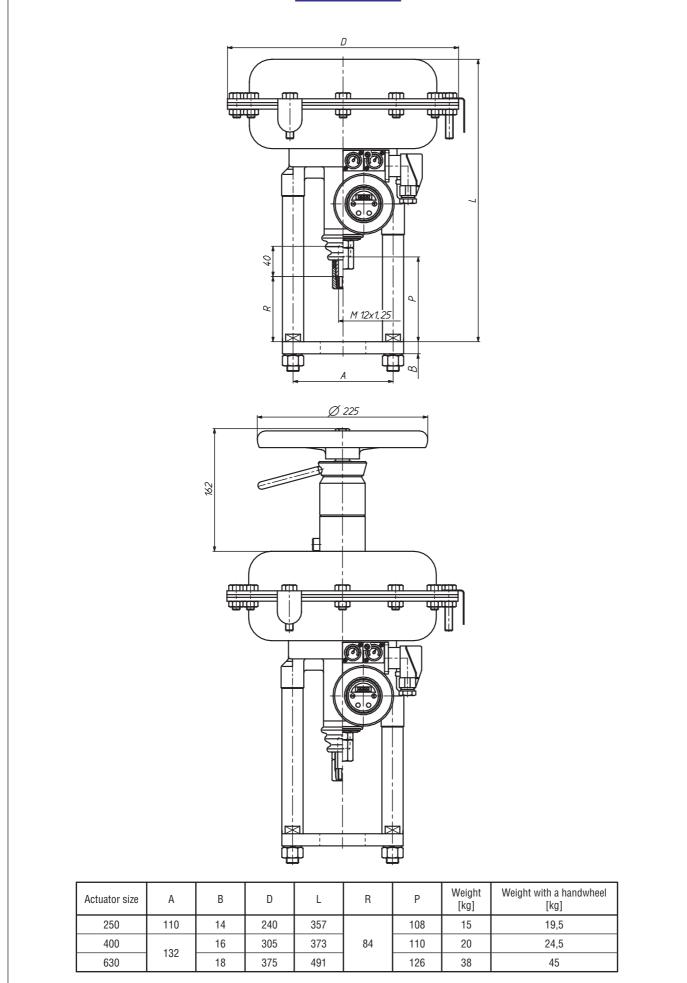
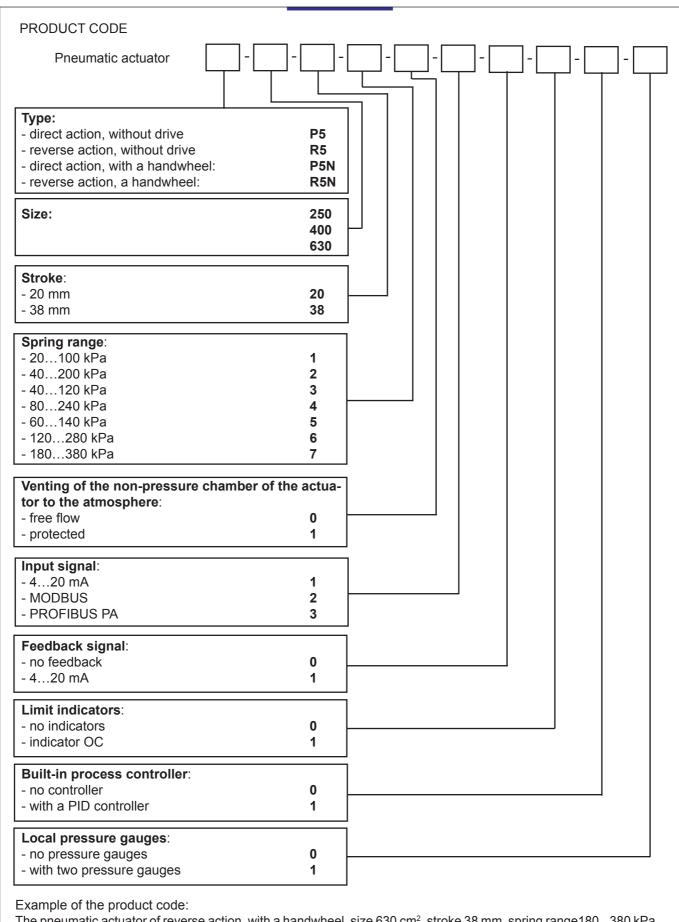


Fig. 6 Dimensions and weights (with the adjuster)



The pneumatic actuator of reverse action, with a handwheel, size 630 cm<sup>2</sup>, stroke 38 mm, spring range 180...380 kPa, venting of the non-pressure chamber of the actuator to the atmosphere protected, input signal 4...20 mA, feedback signal 4...20 mA, no limit indictors, internal PID process controller, with two pressure gauges.

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NOTES:		